

Chapter 2

Estimating the Firing Rate

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Abstract Neuronal activity is measured by the number of stereotyped action potentials, called spikes, elicited in response to a stimulus or the behavioral conditions of an animal. Any nonparametric method for grasping the time-varying rate of spike firing contains a single parameter that controls the jaggedness of the estimated rate, such as the binsize of the time histogram or the bandwidth of the kernel smoother. In most neurophysiological studies, the parameter that determines the interpretation of neuronal activity has been selected subjectively by individual researchers. Recently, theories for objectively selecting the parameter have been developed. This chapter introduces the standard rate estimation tools, such as the peri-stimulus time histogram (PSTH), kernel density estimation, or Bayes estimation, and shows ways of selecting their parameters under the principles of minimizing the mean integrated squared error or maximizing the likelihood. We also sum up the methods in handy recipes that may be useful in practical data analysis.

2.1 Introduction

In the beginning of the last century, Edgar Adrian discerned that a neuron expresses the intensity of a stimulus in the frequency or occurrence rate of stereotyped action potentials (Adrian 1928; Rieke et al. 1997). Since then, the most basic protocol in neurophysiology has been computing the occurrence rate of neuronal action potentials, called spikes or firings, as the correlate of an animal's behavior (Gerstein and Kiang 1960; Johnson 1996; Dayan and Abbott 2001). The rate of neuronal firing, defined in the unit of frequency [Hz], or spikes per second [sp/s], can be computed

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by simply counting the number of spikes and dividing it by the period of the observation interval. Thus the computation of the firing rate is a mere realization of simple descriptive statistics, as exemplified by a census of the population.

However, to grasp the temporal modulation of neuronal activity in relation to sequential behaviors of the animal, one has to go beyond the simple description and treat a hard problem of inferential statistics in estimating an instantaneous rate of firing. If neurons were generating temporally regular spikes, the instantaneous spike rate or the firing frequency may be given by simply inverting the interspike intervals (ISIs). However, this method leads to a messy diagram for highly irregular spike trains recorded from cortical neurons *in vivo*. If, on the contrary, we spend a long time collecting a large number of spikes for precise estimation of the firing rate, we cannot grasp the fine temporal modulation. This seemingly naive issue may arise in any sophisticated method. Any rate estimation tool has a (hyper)parameter, such as the binsize of a time histogram and the bandwidth of a kernel smoother that controls the jaggedness of the estimate. The estimated rate may become highly fluctuating if the binsize or bandwidth is small, and constant in the opposite limit. In neurophysiological studies, the parameter that critically determines the goodness of rate estimation has mostly been selected subjectively by individual researchers.

Originally, neurons generate spikes according to their inputs in a mostly deterministic manner, and there is no definite entity for the firing rate in the brain. The endeavor to capture the rate of spike occurrence from discrete data can be viewed as a process for compressing information. Rate estimation inevitably depends on the method of information compression and is therefore not determined uniquely for a set of data. Nevertheless, the range of plausible principles and estimation methods is limited, and the rate estimated from a given set of data should not vary among principled methods. In applying statistical principles, one views spikes as sample events derived from a certain underlying probabilistic process and strives to estimate the underlying probability from the spike data. In this respect, methods for selecting the parameter based on statistically plausible principles, such as minimizing the mean integrated squared error (MISE) or maximizing the likelihood, have recently been developed.

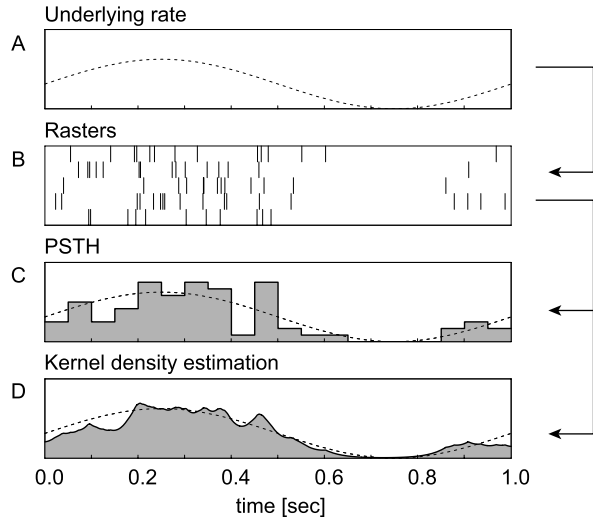
In this chapter, we introduce several standard rate estimation tools, the peristimulus time histogram (PSTH) (Gerstein and Kiang 1960; Abeles 1982), the kernel smoother (Parzen 1962; Richmond et al. 1990; Nawrot et al. 1999), and the Bayesian estimation method, and unfold the principles for optimizing rate estimation methods. These methods are summed up in handy recipes that may be useful for neurophysiologists in analyzing their own data. Package programs are available at

<http://www.ton.scphys.kyoto-u.ac.jp/~shino/toolbox/english.htm> or <http://www.apst.spiketrain-analysis.org/>.

2.2 Methods for Estimating the Firing Rate

Let us first describe how to construct a PSTH and a kernel density estimation, given a set of spike data obtained from repeated trials.

Fig. 2.1 Methods for estimating instantaneous rate. **A:** An underlying spike rate $r(t)$. **B:** Sample spike raster diagrams for five trials. **C:** A peri-stimulus time histogram (PSTH). **D:** A kernel density estimation



2.2.1 PSTH

A histogram is a realization of a simple counting method and can be constructed from a set of spike trains, according to the following instructions (Figs. 2.1A–C).

A method for constructing a PSTH

1. Align n spike trains at the onset or offset of stimuli.
2. Divide an observation period T into intervals of width Δ .
3. Count spikes collected from all trials as k_i for i th bin.
4. Draw a bar at the height $k_i/(n\Delta)$ in a time period of $[(i-1)\Delta, i\Delta]$.
5. Repeat 3 and 4 for each bin from $i = 1$ to $N_b (= T/\Delta)$.

In many neurophysiological papers, the height of the PSTH is represented by the raw spike count per bin. We recommend representing the height of the PSTH in the units of spike rate for one trial, so that integration over the period T gives the number of spikes averaged over trials. Due to this normalization procedure, the heights of PSTHs obtained with different binsize Δ should be approximately equal, and estimates can be compared across different binsizes.

2.2.2 The Kernel Density Estimation

A kernel density estimation can be obtained by blurring each spike with a kernel function, according to the following instructions (Figs. 2.1A, B, and D).

A method for constructing a kernel density estimation

1. Align n spike trains at the onset or offset of stimuli.
2. At every spike, apply a kernel function $f_{\Delta}(t)$ of bandwidth Δ .
3. Divide the summed function by the number of trials n , or

$$\hat{r}(t) = \frac{1}{n} \sum_{j=1}^n \sum_{i=1}^{N_s^j} f_{\Delta}(t - t_i^j), \quad (2.1)$$

where t_i^j is the time of the i th spike in the j th trial, and N_s^j is the total number of spikes recorded in the j th trial.

The height of the density estimation measures the spike rate per one trial, similar to the above-mentioned PSTH. The filtering kernel should satisfy the normalization to unit area, $\int f(t) dt = 1$. The kernel is normally assumed to be nonnegative, $f(t) \geq 0$, and to have a finite bandwidth defined by the variance that is normally finite, $\Delta^2 = \int t^2 f(t) dt < \infty$, and is often chosen to be symmetric, $f(t) = f(-t)$. Many kernel functions satisfy these conditions (Paulin 1992; Nawrot et al. 1999; Paulin and Hoffman 2001; Cherif et al. 2008): A rectangular “boxcar” kernel may give rise to a jagged density function with an appearance similar to that of the PSTH. The width of the boxcar should be $2\sqrt{3}\Delta$ in order to give the variance of Δ^2 ,

$$f_{\Delta}(t) = \begin{cases} \frac{1}{2\sqrt{3}\Delta} & \text{for } -\sqrt{3}\Delta \leq t \leq \sqrt{3}\Delta, \\ 0 & \text{otherwise.} \end{cases} \quad (2.2)$$

A smooth density estimation can be obtained by using a smooth kernel such as the Gaussian function,

$$f_{\Delta}(t) = \frac{1}{\sqrt{2\pi}\Delta} \exp\left(-\frac{t^2}{2\Delta^2}\right). \quad (2.3)$$

Alternatively, emphasis may be put on the evidence for spike occurrence from the cusp of the exponential kernel,

$$f_{\Delta}(t) = \frac{1}{\sqrt{2}\Delta} \exp\left(-\sqrt{2}\left|\frac{t}{\Delta}\right|\right). \quad (2.4)$$

It is noteworthy that exponential functions turn out to be the optimal kernels under the MISE minimization principle for several underlying rates (Koyama and Shinomoto 2004).

Both the Gaussian kernel (2.3) and the exponential kernel (2.4) have infinite support. However, since they decay rapidly, they can be approximated as functions with compact support. For instance, the normalization condition to unit area is in practice not violated even if we cut them off outside the range of $\pm 5\Delta$; the integrated areas

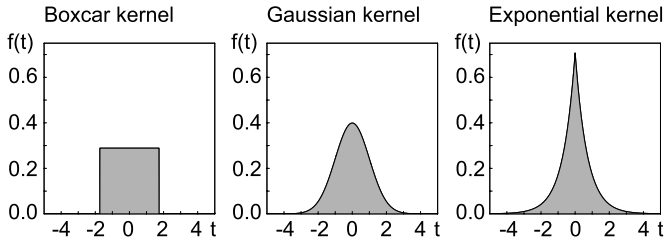


Fig. 2.2 The boxcar, Gaussian, and exponential kernels that give an identical bandwidth, or the variance $\int t^2 f(t) dt = 1$

$\int_{-5\Delta}^{5\Delta} f_{\Delta}(t) dt$ become 0.999999 and 0.999151, respectively, for the Gaussian and exponential kernels, thus practically losing nothing in both cases. (See Fig. 2.2.)

2.3 Methods for Optimizing the Rate Estimation

For a single set of spike trains, either a PSTH or a kernel density estimation is not given uniquely, and its shape depends greatly on the choice of the binsize or bandwidth. Figure 2.3 exemplifies three PSTHs constructed from an identical set of spike trains. If the binsize is too small, the time histogram fluctuates greatly, and one cannot discern the underlying spike rate, whereas if it is too large, one cannot capture the time dependence of the rate. There would be an appropriate binsize or bandwidth for each set of spike sequences, based on the goodness-of-fit of a PSTH or a kernel density estimation.

Several plausible principles exist for the goodness-of-fit of the estimator. Here, we introduce two of them and demonstrate formulae that may be practically useful in the application to spike data. One is the principle of minimizing the distance between the estimated rate and the unknown underlying rate measured in the MISE, and another is the principle of maximizing the likelihood function for a given set of data.

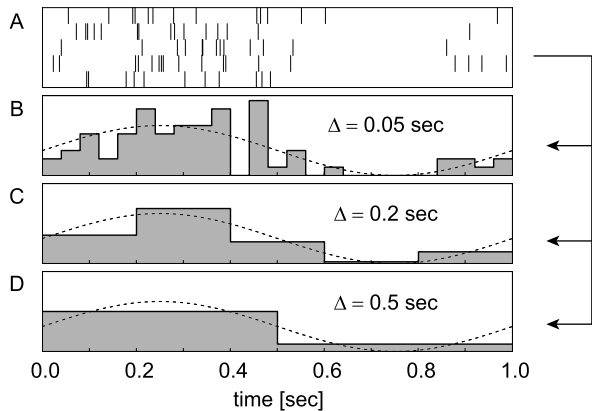


Fig. 2.3 Time histograms with various binsizes. **A:** Spike data given in Fig. 2.1. **B–D:** The time histograms constructed with small, medium, and large binsizes. *Dashed line* represents the underlying rate $r(t)$ from which the spikes were derived

2.3.1 MISE Principle

First, we select the binsize or the bandwidth parameter Δ such that the PSTH or the kernel rate estimator $\hat{r}_\Delta(t)$ best approximates the underlying rate $r(t)$ under the principle of minimizing the MISE,

$$\text{MISE}(\Delta) \equiv \frac{1}{T} \int_0^T E(\hat{r}_\Delta(t) - r(t))^2 dt, \quad (2.5)$$

where E refers to the expectation over different realizations of point events, given $r(t)$.

The definition of MISE contains the underlying rate $r(t)$ itself, which is unknown by nature. Nevertheless, using the spike data as a clue, it is possible to minimize the expected MISE with respect to the parameter Δ (Rudemo 1982; Shimazaki and Shinomoto 2007a, 2007b, 2010). Note that the optimization method can be derived rigorously without assuming anything about the time-dependent rate $r(t)$, such as the continuity of the rate. The only assumption needed in deriving the rule is that spikes are drawn from an inhomogeneous Poisson process in which spikes are independently derived from an underlying rate $r(t)$. Though spikes recorded from a biological neuron correlate in each sequence (Shinomoto et al. 2003, 2005, 2009), spikes collected from a number of independent trials are statistically independent, and the superimposed sequence can be approximated as a single inhomogeneous Poisson process (Snyder 1975; Daley and Vere-Jones 2003; Kass et al. 2005).

2.3.1.1 MISE Optimization of PSTH

Leaving the derivation of the rule for minimizing MISE for the PSTH to the literature (Shimazaki and Shinomoto 2007a), we introduce the method of selecting the binsize Δ in a form of a simple recipe in the following.

A method for selecting the binsize of PSTH

1. Compute the average \bar{k} and the variance v of the spike counts $\{k_i\}$ for all bins, $i = 1, 2, \dots, N_b$,

$$\bar{k} \equiv \frac{1}{N_b} \sum_{i=1}^{N_b} k_i, \quad (2.6)$$

$$v \equiv \frac{1}{N_b} \sum_{i=1}^{N_b} (k_i - \bar{k})^2, \quad (2.7)$$

and evaluate the cost function (Shimazaki and Shinomoto 2007a),

$$C(\Delta) = \frac{2\bar{k} - v}{(n\Delta)^2}, \quad (2.8)$$

where n is the number of trials, and Δ is the binsize.

2. Repeat 1 by moving the initial binning position to take an average of $C(\Delta)$.
3. Repeat 2 while changing Δ to draw the cost as a function of the bin size.
4. The MISE optimal binsize Δ^* is given by the one that minimizes $C(\Delta)$.

Note here that the variance v is not the unbiased variance, but the biased variance as defined by (2.7). The averaging of $C(\Delta)$ over the initial binning positions is useful for limiting the possible fluctuation due to the finiteness of data. Figure 2.4 displays the raw and averaged cost functions computed for the set of spike data given in Fig. 2.3, demonstrating significant fluctuation for a raw cost function.

By applying the optimization method to spike trains whose intensity does not modulate greatly in time, it might come to pass that the original cost function $C(\Delta)$ computed for n spike sequences does not have a minimum or has a minimum at a binsize comparable to the observation period T . This implies that the data are insufficient for estimating the time-dependent rate. The divergence of Δ^* implies that any PSTH of a finite binsize captures a spurious rate and therefore is worse than simply drawing a constant rate, in the sense of MISE (Koyama and Shinomoto 2004). This cost function evaluation may be useful in justifying the estimation of the time-dependent rate, in particular for discussing the presence or absence of oscillatory activity.

Because a shortage of data underlies the divergence of the optimized binsize, one would consider carrying out more experiments to obtain reliable rate estimation. In making the experimental plan, one may want to estimate how many experiments should be added to secure the PSTH resolution one deems sufficient. This can be done through extrapolating the cost function $C(\Delta)$ obtained with a given number of trials n to the case of a different number of trials m , as

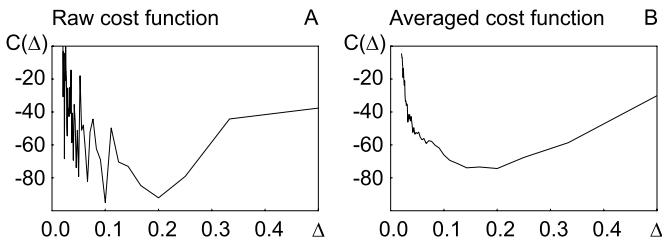


Fig. 2.4 The cost functions $C(\Delta)$ obtained for the set of spike data given in Fig. 2.1B. **A:** Raw cost function obtained for a single set of counting statistics ($\Delta^* = 0.1$). **B:** The cost function averaged over the initial binning positions ($\Delta^* = 0.2$)

$$C(\Delta|m) = \left(\frac{1}{m} - \frac{1}{n}\right) \frac{\bar{k}}{n\Delta^2} + C(\Delta), \quad (2.9)$$

where \bar{k} is the average spike count (2.6) obtained from n sequences. Even if the optimal binsize Δ^* diverged for a given number of spike sequences, implying the incapability of drawing a meaningful PSTH, one can still estimate the number of additional experimental trials needed to make the optimal binsize finite, justifying the evaluation of the time-dependent rate from the data.

It is also possible to extend the estimation method from the bar-graph PSTH to the line-graph PSTH, which generally provides a superior goodness-of-fit (Koyama and Shinomoto 2004). We do not go into the details of the line-graph histogram optimization, which is more complicated than the optimization method presented here (Shimazaki and Shinomoto 2007a).

2.3.1.2 MISE Optimization of Kernel Density Estimation

The same principle of minimizing the MISE can also be applied to the kernel density estimation (Shimazaki and Shinomoto 2007b, 2010). Leaving the derivation of the rule to the literature, we introduce the method of selecting the bandwidth Δ in a form of a simple recipe in the following.

A method for selecting the bandwidth of the kernel density estimator

1. Compute the cost function (Shimazaki and Shinomoto 2007b, 2010)

$$C(\Delta) = \frac{1}{n^2} \sum_{i,j} \phi_{\Delta}(t_i - t_j) - \frac{2}{n^2} \sum_{i \neq j} f_{\Delta}(t_i - t_j), \quad (2.10)$$

where $\phi_{\Delta}(t_i - t_j) \equiv \int f_{\Delta}(s - t_i) f_{\Delta}(s - t_j) ds$.

2. Repeat 1 while changing Δ to draw the cost as a function of the bandwidth.
3. The MISE optimal bandwidth Δ^* is given by the one that minimizes $C(\Delta)$.

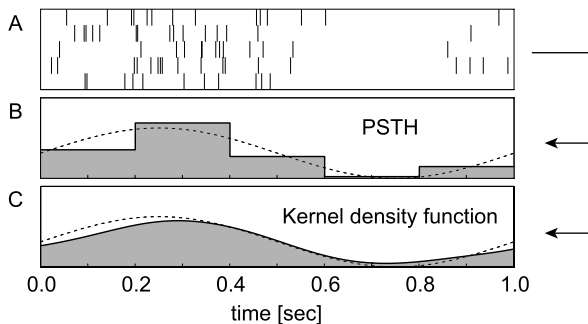
Note here that the computational cost can be significantly reduced by neglecting unnecessary parts in the double summation in (2.10), based on the practical compactness of either the Gaussian or the exponential kernel. In addition, the convoluted function is given simply as $\phi_{\Delta}(t) = 1/(2\sqrt{\pi}\Delta) \exp(-t^2/4\Delta^2)$, for the Gaussian kernel, $f_{\Delta}(t) = 1/(\sqrt{2\pi}\Delta) \exp(-t^2/2\Delta^2)$.

Kernel density estimation with a smooth kernel function is generally much superior to PSTH in its goodness-of-fit to the underlying rate, as demonstrated in Fig. 2.5.

2.3.1.3 TIPS

Application programs for optimizing the PSTH and kernel density estimation methods under the MISE principle were provided by Hideaki Shimazaki at

Fig. 2.5 Comparison of the optimized PSTH and optimized kernel density estimator. **A:** Spike data given in Fig. 2.1. **B:** The time histograms of the optimal binsize $\Delta^* = 0.2$. **C:** The Gaussian kernel density estimation of the optimal bandwidth $\Delta^* = 0.1$



<http://www.ton.scphys.kyoto-u.ac.jp/~shino/toolbox/sshist/hist.html> or <http://www.apst.spiketrain-analysis.org/>

and

<http://www.ton.scphys.kyoto-u.ac.jp/~shino/toolbox/sskernel/kernel.html> or <http://www.apst.spiketrain-analysis.org/>.

By simply copying and pasting a data set of spike times to the application, one can obtain the optimal binsize or bandwidth Δ^* for the PSTH or the kernel, and a list of $\{t, \hat{r}_{\Delta^*}(t)\}$, with which to draw the PSTH or kernel density function. One may also download MATLAB codes for these optimization algorithms.

2.3.2 Likelihood Principle

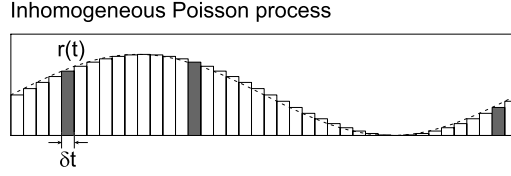
Another standard optimization principle is maximizing the likelihood. This can be done by treating a rate function $r(t)$ as a distribution function of spike times. If one does not have a prior idea for a particular set of rate functions, one may construct a rate estimator nonparametrically. However, one still needs to determine a (hyper)parameter for the smoothness or jaggedness of the estimator. Here, we introduce a relatively simple Bayesian method (Koyama and Shinomoto 2005; Koyama et al. 2007; Shimokawa and Shinomoto 2009) and show the ways to determine a hyperparameter that plays a role similar to the bandwidth of the filtering kernel.

2.3.2.1 Empirical Bayes Method of Rate Estimation

Let us first consider a time-dependent Poisson process in which spikes are derived randomly in time from a given underlying rate $r(t)$. In this process, the probability for spikes to occur at $\{t_i\} \equiv \{t_1, t_2, \dots, t_{N_s}\}$ in the period of $t \in [0, T]$ is given by

$$p(\{t_i\} | r(t)) = \left[\prod_{i=1}^{N_s} r(t_i) \right] \exp\left(-\int_0^T r(t) dt\right). \quad (2.11)$$

Fig. 2.6 The rate-modulated Poisson process. The probability for a spike to occur in each short interval δt is $r(t)\delta t \ll 1$, and the probability of having no spike is $1 - r(t)\delta t \approx \exp(-r(t)\delta t)$



Here the exponential term is the survivor function that represents the probability that spikes have not occurred in the interval (Cox and Lewis 1966; Daley and Vere-Jones 2003): The probability for a spike to occur in each short interval of δt is $r(t)\delta t \ll 1$ (see Fig. 2.6), and the probability of having no spike from the time t_1 to t_2 is given by

$$\lim_{\delta t \rightarrow 0} \prod_m (1 - r(t_m)\delta t) = \exp\left(-\int_{t_1}^{t_2} r(t) dt\right).$$

We invert the arguments of the conditional probability (2.11) so that the unknown underlying rate is inferred from the spikes observed. This “inverse probability” can be obtained using the Bayes formula

$$p_\beta(r(t) | \{t_i\}) = \frac{p(\{t_i\} | r(t))p_\beta(r(t))}{p_\beta(\{t_i\})}. \quad (2.12)$$

As a Bayesian prior distribution of $r(t)$, we incorporate the tendency of the estimated rate to be flat by penalizing the large gradient, $|dr(t)/dt|$,

$$p_\beta(r(t)) \propto \exp\left[-\beta \int_0^T \left(\frac{dr(t)}{dt}\right)^2 dt\right], \quad (2.13)$$

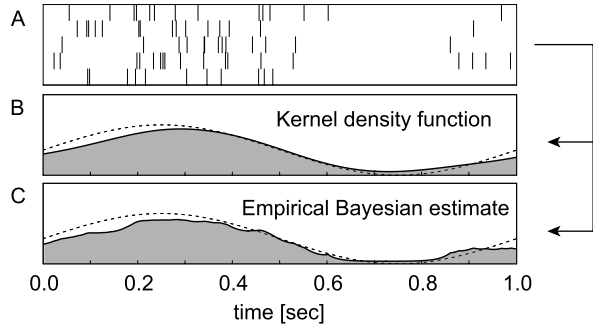
where β is a hyperparameter representing the “flatness”; the estimated rate becomes insensitive/sensitive to individual spike occurrences as β is large/small. The flatness may be replaced by the smoothness by changing the first-order derivative to the second-order derivative. The result of the inference is known to be robust to the order of differentiation in the prior distribution (Nemenman and Bialek 2002). The probability of having spikes at $\{t_i\} \equiv \{t_1, t_2, \dots, t_{N_s}\}$ is given by the “marginal likelihood function” or the “evidence,”

$$p_\beta(\{t_i\}) = \int D\{r(t)\} p(\{t_i\} | r(t)) p_\beta(r(t)), \quad (2.14)$$

where $\int D\{r(t)\}$ represents a functional integration over all possible paths of the unknown underlying rate $r(t)$. The method of selecting the hyperparameter according to the principle of maximizing the marginal likelihood function is called the Empirical Bayes method (Good 1965; Akaike 1980; MacKay 1992; Carlin and Louis 2000). The marginalization path integral (2.14) for a given set of spike data $\{t_i\}$ can be carried out by the Expectation Maximization (EM) method (Dempster et al. 1977; Smith and Brown 2003) or the Laplace approximation (Koyama and Paninski 2009). With the hyperparameter determined as $\beta = \beta^*$, we can further obtain the maximum a posteriori (MAP) estimate of the rate $\hat{r}(t)$, so that their posterior distribution,

$$p_{\beta^*}(r(t) | \{t_i\}) \propto p(\{t_i\} | r(t)) p_{\beta^*}(r(t)), \quad (2.15)$$

Fig. 2.7 Comparison of the optimized kernel density estimator and Empirical Bayes rate estimator. **A:** Spike data given in Fig. 2.1. **B:** The kernel density estimation of the optimal binsize $\Delta^* = 0.1$. **C:** The MAP rate estimate of the Empirical Bayes method



is maximized. The MAP estimate resembles the kernel filtering method in that the estimated rate $\hat{r}(t)$ is lifted at every spike. The Bayesian MAP rate estimate gives a similar result to the optimized kernel density estimator for a given set of data (Fig. 2.7). With the flatness constant β large/small, the rate estimation becomes insensitive/sensitive to individual spike occurrences. Here we outline the algorithms for maximizing the marginalized likelihood (2.14) by using the EM method, and Kalman filtering and smoothing or “point-process filtering” (Brown et al. 1998) for a given set of spike trains.

An Empirical Bayes method for estimating the rate

1. Perform the marginalization path integral (2.14) using a state-space model or the hidden Markov model, in which the rates and spikes are treated as states and observations, respectively defined at every time a spike occurred.
2. Optimize the hyperparameter by the EM method.
3. Obtain the expected values and the expected variances of the latent variables with Kalman filtering and smoothing.

2.3.2.2 TIPS

An application program that helps the readers to analyze their own neuronal data with the Empirical Bayesian rate estimation was provided by Takeaki Shimokawa at

<http://www.ton.scphys.kyoto-u.ac.jp/~shino/toolbox/ssBayes/bayes.html> or <http://www.apst.spiketrain-analysis.org/>.

By simply copying and pasting a data set of spike times, one may obtain the MAP estimate of the rate and a list of $\{t, \hat{r}(t)\}$, with which one can draw the Bayesian

estimation of the rate. The extension to the simultaneous estimation of the rate and the instantaneous irregularity is given at

http://www.ton.scphys.kyoto-u.ac.jp/~shino/toolbox/ssNeCo09/page_SULAB2.html or <http://www.apst.spiketrain-analysis.org/>

which are based on the theory developed in Shimokawa and Shinomoto (2009).

2.4 Discussion

In this chapter, we introduced typical rate estimation methods, the PSTH, kernel density estimation, and Bayesian estimation. We also demonstrated optimization of the PSTH and the kernel method under the principle of minimizing the MISE and optimizing the Bayesian rate estimation under the principle of maximizing the likelihood function.

Those who intended to practically perform rate estimation may waver regarding the choice of the multiple methods of rate estimation and multiple principles for parameter optimization to use. There is in fact no oracle that may select one of the different optimization principles, and therefore one may choose any of them. Nevertheless, one may expect that reasonable optimization principles provide similar rate estimations for a given set of spike data. It is interesting in this respect to examine whether the different methods may give qualitatively different conclusions for the detectability of rate modulation. For a small number of spike trains derived from an underlying rate $r(t)$ that fluctuates moderately in time, the optimal binsize may diverge, indicating the incapability of detecting a time-dependent rate. For a doubly stochastic process in which the rate is modulated according to the Ornstein–Uhlenbeck process, we may analytically obtain the conditions for the divergence of the optimized binsize Δ^* (Koyama and Shinomoto 2004) and the optimized flatness constant β^* (Koyama et al. 2007). It is noteworthy that both parameters Δ^* and β^* diverge for the identical condition, $n\sigma^2\tau/\mu \leq 1/2$, where the μ , σ^2 , and τ are the mean, variance, and timescale of rate fluctuation, respectively. This implies that the different principles such as MISE minimization for a PSTH and marginal likelihood maximization for the Bayes estimation may render similar detectability for rate modulation.

Though these optimization principles may provide reasonable rate estimations, there may still be room for improvement. The practical problem we did not consider in this chapter is the nonstationarity of the rate, such that neuronal activity exhibits abrupt changes in response to a stimulus given to an animal. In such a case, it would be more efficient to modulate the hyperparameter according to the time-varying circumstances. Methods have been proposed for locally adaptive determination of hyperparameters (Abramson 1982; Sain and Scott 1996, 2002; Loader 1999a, 1999b; DiMatteo et al. 2001; Kass et al. 2003; Endres et al. 2008; Shimazaki and Shinomoto 2010).

When applying any sophisticated optimization method to neurophysiological data, one might feel the optimized binsize or bandwidth to be larger than expected.

In practice, the PSTH binsize chosen in neurophysiological literature has tended to be much smaller than the optimal one. This would be because we are inclined to see the details rather than to ignore unnecessary parts. Therefore, the choice lies with the researcher to not use any of the optimization principles. However, there are circumstances in which objective optimization principles are essential. The most important application of the optimal rate estimation method would be the detectability of a significant rate modulation, such as oscillation in neuronal firing. The presence of rate modulation may be judged from the finiteness of the optimal binsize or bandwidth and the systematic modulation of the estimated rate.

Another important application of rate estimation is the analysis of the intrinsic regularity of neuronal firing: It has been revealed that neuronal firing bears non-Poisson aspects; the spike occurrence depends on the preceding spike. The neuronal firing patterns have been analyzed by paying attention to the variability of ISIs (Kuffler et al. 1957; Gerstein and Mandelbrot 1964; Stein 1965; Baker and Lemon 2000; Barbieri et al. 2001; Oram et al. 1999; Kostal and Lansky 2006). However, ISI analysis is vulnerable to firing rate fluctuation, which tends to broaden the ISI distribution and makes the regular sequence evaluated closer to Poissonian randomness. The analysis of firing patterns includes an essential difficulty in its definition of firing regularity. An apparently random sequence of spikes can be interpreted as being derived either irregularly in time from a constant rate or regularly from a fluctuating rate. To determine which interpretation is more plausible in any given case, we introduced a metric measuring the ISI variability rescaled locally in time (Shinomoto et al. 2003, 2005, 2009) and also considered rescaling the sequence of spikes by the instantaneous firing rate (Reich et al. 1998; Koyama and Shinomoto 2005; Nawrot et al. 2008; Shimokawa and Shinomoto 2009). To carry out the time rescaling correctly, one needs to accurately estimate the instantaneous rate. Inversely, the information on firing regularity may be used in improving the firing rate estimation (Cunningham et al. 2008). In this way, the rate and the regularity are complementary aspects of a single spike train; this interesting issue will be discussed in other chapters in more detail (Chaps. 1, 3).

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